

# **Catalogue**

## **Open Loop Hall Effect AC Current Sensors/ Transducers with Round Window**

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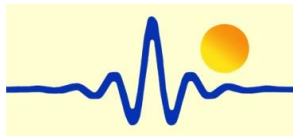
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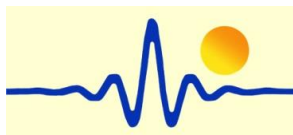




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## Hall Effect AC Current Sensor CYHCS-C1TV

This Hall Effect current sensor is based on open loop principle and designed with a high galvanic isolation between primary conductor and secondary circuit. It can be used for measurement of AC current, pulse currents etc. The output of the transducer reflects the rectified average value of the current in the carrying conductor.

Product Characteristics	Applications
<ul style="list-style-type: none"> <li>Excellent accuracy</li> <li>Very good linearity</li> <li>Light in weight</li> <li>Less power consumption</li> <li>Window structure</li> <li>Electrically isolating the output of the transducer from the current carrying conductor</li> <li>No insertion loss</li> <li>Current overload capability</li> </ul>	<ul style="list-style-type: none"> <li><b>Photovoltaic equipment</b></li> <li>Frequency conversion timing equipment</li> <li>Various power supply</li> <li>Uninterruptible power supplies (UPS)</li> <li>Electric welding machines</li> <li>Numerical controlled machine tools</li> <li>Electrolyzing and electroplating equipment</li> <li>Electric powered locomotive</li> <li>Microcomputer monitoring</li> <li>Electric power network monitoring</li> </ul>

### Electrical Data

Primary Nominal RMS Current $I_r$ (A)	Measuring Range (A)	DC Output Voltage (V)	Aperture Diameter (mm)	Part number
25	0-25	$x=0$ : 0-4V $\pm 1.0\%$ $x=3$ : 0-5V $\pm 1.0\%$ $x=8$ : 0-10V $\pm 1.0\%$	$\varnothing 20$	CYHCS-C1TV-25A-xnC
30	0-30			CYHCS-C1TV-30A-xnC
40	0-40			CYHCS-C1TV-40A-xnC
50	0-50			CYHCS-C1TV-50A-xnC
100	0-100			CYHCS-C1TV-100A-xnC
200	0-200			CYHCS-C1TV-200A-xnC
300	0-300			CYHCS-C1TV-300A-xnC
400	0-400			CYHCS-C1TV-400A-xnC
500	0-500			CYHCS-C1TV-500A-xnC
600	0-600			CYHCS-C1TV-600A-xnC

( $n=2$ ,  $V_{cc}=+12VDC \pm 5\%$ ;  $n=3$ ,  $V_{cc}=+15VDC \pm 5\%$ ;  $n=4$ ,  $V_{cc}=+24VDC \pm 5\%$ )  
(Connector: Molex connector C=M; Phoenix Connector: C=P)

Supply Voltage:	$V_{cc}=+12V, +15V, +24V \pm 5\%$
Current Consumption	$I_c < 25mA$
Isolation Voltage	2.5kV, 50/60Hz, 1min
Output Impedance:	$R_{out} < 150\Omega$
Load Resistor:	$R_L > 10k\Omega$
Accuracy at $I_r$ , $T_A=25^\circ C$ ,	$X < 1.0\% FS$
Linearity from 0 to $I_r$ , $T_A=25^\circ C$ ,	$E_L < 1.0\% FS$
Electric Offset Voltage, $T_A=25^\circ C$ ,	$V_{oe} < 50mV$
Magnetic Offset Voltage ( $I_r \rightarrow 0$ )	$V_{om} < \pm 20mV$
Thermal Drift of Offset Voltage,	$V_{ot} < \pm 1.0mV/^\circ C$
Thermal Drift ( $-10^\circ C$ to $50^\circ C$ ),	T.C. $< \pm 0.1\% / ^\circ C$
Response Time at 90% of $I_p$ ( $f=1k Hz$ )	$t_r < 200ms$
Frequency Bandwidth (-3dB),	$f_b = 20Hz - 20 kHz$
Case Material:	PBT, heat resistant 100°C flame retardant



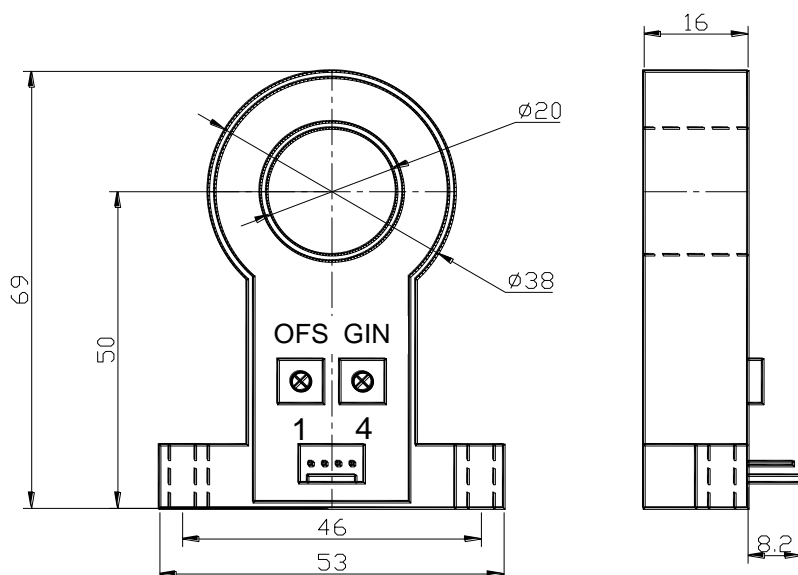


## General Data

Ambient Operating Temperature,  
Ambient Storage Temperature,

$T_A = -25^{\circ}\text{C} \sim +85^{\circ}\text{C}$   
 $T_S = -55^{\circ}\text{C} \sim +100^{\circ}\text{C}$

## PIN Definition and Dimensions

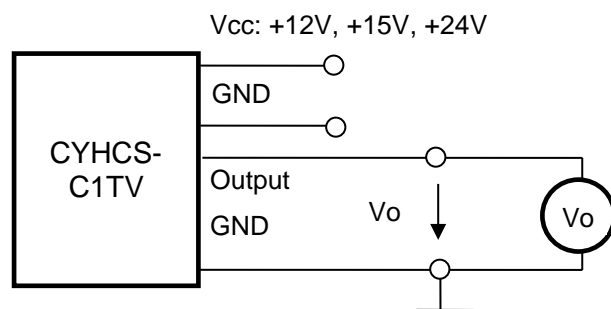


1(+): Vcc  
2(G): GND  
3(O): Output  
4(G): GND

OFS: Offset Adjustment

GIN: Gain Adjustment

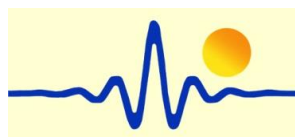
## Connection



## Notes:

1. Connect the terminals of power source, output respectively and correctly, never make wrong connection.
2. Two potentiometers can be adjusted, only if necessary, by turning slowly to the required accuracy with a small screwdriver.
3. The best accuracy can be achieved when the window is fully filled with bus-bar (current carrying conductor).
4. The in-phase output can be obtained when the direction of current of current carrying conductor is the same as the direction of arrow marked on the transducer





## Hall Effect AC Current Sensor CYHCS-C1TC

This Hall Effect current sensor is based on open loop principle and designed split a high galvanic isolation between primary conductor and secondary circuit. It can be used for measurement of AC current, pulse currents etc. The output of the transducer reflects the rectified average value of the current in the carrying conductor.

Product Characteristics	Applications
<ul style="list-style-type: none"> <li>Excellent accuracy</li> <li>Very good linearity</li> <li>easy mounting</li> <li>Less power consumption</li> <li>Window structure</li> <li>Electrically isolating the output of the transducer from the current carrying conductor</li> <li>No insertion loss</li> <li>Current overload capability</li> </ul>	<ul style="list-style-type: none"> <li><b>Photovoltaic equipment</b></li> <li>Frequency conversion timing equipment</li> <li>Various power supply</li> <li>Uninterruptible power supplies (UPS)</li> <li>Electric welding machines</li> <li>Transformer substation</li> <li>Numerical controlled machine tools</li> <li>Electric powered locomotive</li> <li>Microcomputer monitoring</li> <li>Electric power network monitoring</li> </ul>

### Electrical Data

Primary Nominal RMS Current $I_r$ (A)	Measuring Range (A)	DC Output Current (mA)	Aperture Diameter (mm)	Part number
25	0~25	4-20 $\pm 1.0\%$	$\varnothing 20$	CYHCS-C1TC-25A-nC
30	0~30			CYHCS-C1TC-30A-nC
40	0~40			CYHCS-C1TC-40A-nC
50	0~50			CYHCS-C1TC-50A-nC
100	0~100			CYHCS-C1TC-100A-nC
200	0~200			CYHCS-C1TC-200A-nC
300	0~300			CYHCS-C1TC-300A-nC
400	0~400			CYHCS-C1TC-400A-nC
500	0~500			CYHCS-C1TC-500A-nC
600	0~600			CYHCS-C1TC-600A-nC

(n=3,  $V_{cc} = +12VDC \pm 5\%$ ; n=4,  $V_{cc} = +15VDC \pm 5\%$ ; n=5,  $V_{cc} = +24VDC \pm 5\%$ )

(Connector: Molex connector C=M; Phoenix Connector: C=P)

Supply Voltage

$V_{cc} = +12V, +15V, +24V \pm 5\%$

Current Consumption

$I_c < 25mA + \text{Output current}$

Galvanic isolation, 50/60Hz, 1min:

2.5kV

Isolation resistance @ 500 VDC

> 500 M $\Omega$

### Accuracy and Dynamic performance data

Accuracy at  $I_r$ ,  $T_A = 25^\circ C$ ,

<1.0% FS

Linearity from 0 to  $I_r$ ,  $T_A = 25^\circ C$ ,

$E_L < 1.0\%$  FS

Electric Offset Current,  $T_A = 25^\circ C$ ,

4mA DC

Thermal Drift of Offset Current,

< $\pm 0.005mA/^\circ C$

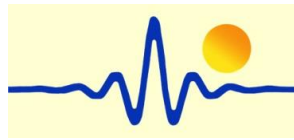
Response Time at 90% of  $I_P$

$t_r < 200ms$

Load resistance:

80-450 $\Omega$





Frequency bandwidth (- 3 dB):  
Case Material:

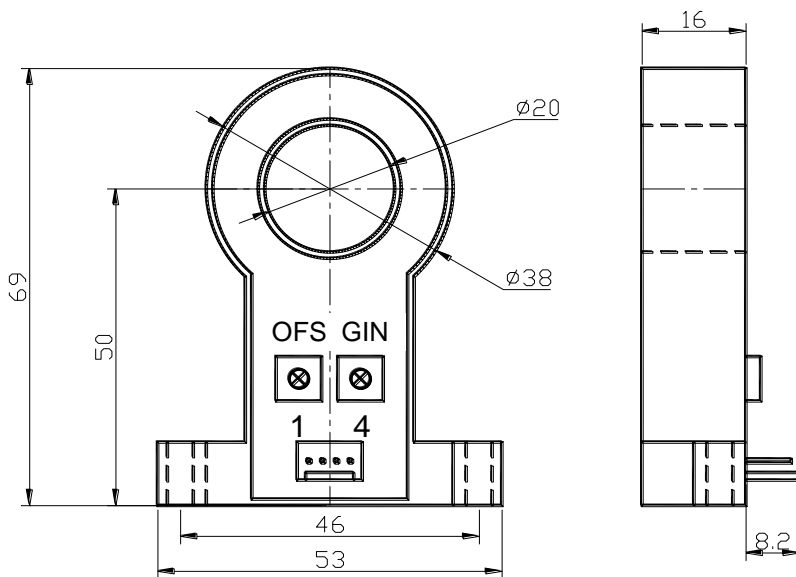
20Hz - 20kHz  
PBT, heat resistant 100°C flame retardant

## General Data

Ambient Operating Temperature,  
Ambient Storage Temperature,

$T_A = -25^{\circ}\text{C} \sim +85^{\circ}\text{C}$   
 $T_S = -40^{\circ}\text{C} \sim +100^{\circ}\text{C}$

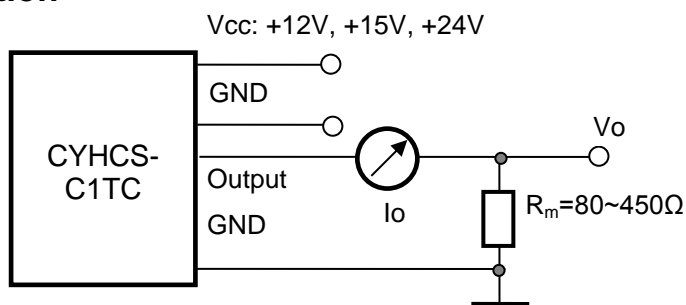
## PIN Definition and Dimensions



1(+): Vcc  
2(G): GND  
3(O): Output  
4(G): GND

OFS: Offset Adjustment      GIN: Gain Adjustment

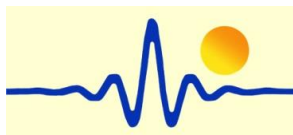
## Connection



## Notes:

1. Connect the terminals of power source, output respectively and correctly, never make wrong connection.
2. Two potentiometers can be adjusted, only if necessary, by turning slowly to the required accuracy with a small screwdriver.
3. The best accuracy can be achieved when the window is fully filled with bus-bar (current carrying conductor).
4. The in-phase output can be obtained when the direction of current of current carrying conductor is the same as the direction of arrow marked on the transducer





## Split Core Hall Effect AC Current Sensor CYHCS-C2TV

This Hall Effect current sensor is based on open loop principle and designed with a split core and a high galvanic isolation between primary conductor and secondary circuit. It can be used for measurement of AC current, pulse currents etc. The output of the transducer reflects the rectified average value of the current in the carrying conductor.

Product Characteristics	Applications
<ul style="list-style-type: none"> <li>Excellent accuracy</li> <li>Very good linearity</li> <li>Light in weight</li> <li>Less power consumption</li> <li>Window structure</li> <li>Electrically isolating the output of the transducer from the current carrying conductor</li> <li>No insertion loss</li> <li>Current overload capability</li> </ul>	<ul style="list-style-type: none"> <li><b>Photovoltaic equipment</b></li> <li>Frequency conversion timing equipment</li> <li>Various power supply</li> <li>Uninterruptible power supplies (UPS)</li> <li>Electric welding machines</li> <li>Numerical controlled machine tools</li> <li>Electrolyzing and electroplating equipment</li> <li>Electric powered locomotive</li> <li>Microcomputer monitoring</li> <li>Electric power network monitoring</li> </ul>

### Electrical Data/Input

Primary Nominal rms Current $I_r$ (A)	Primary Current Measuring Range $I_p$ (A)	DC Output Voltage (V)	Part number
25A	0 ~ 25A	x=0: 0-4V $\pm 1.0\%$ x=3: 0-5V $\pm 1.0\%$ x=8: 0-10V $\pm 1.0\%$	CYHCS-C2TV-25A-xnC
30A	0 ~ 30A		CYHCS-C2TV-30A-xnC
40A	0 ~ 40A		CYHCS-C2TV-40A-xnC
50A	0 ~ 50A		CYHCS-C2TV-50A-xnC
100A	0 ~ 100A		CYHCS-C2TV-100A-xnC
200A	0 ~ 200A		CYHCS-C2TV-200A-xnC
300A	0 ~ 300A		CYHCS-C2TV-300A-xnC
400A	0 ~ 400A		CYHCS-C2TV-400A-xnC
500A	0 ~ 500A		CYHCS-C2TV-500A-xnC
600A	0 ~ 600A		CYHCS-C2TV-600A-xnC

(n=2,  $V_{cc}=+12VDC$ ; n=3,  $V_{cc}=+15VDC$ ; n=4,  $V_{cc}=+24VDC$ )

(Connector: Molex connector C=M; Phoenix Connector: C=P)

Supply Voltage:

Current Consumption

Isolation Voltage

Output Impedance:

Load Resistor:

Accuracy at  $I_r$ ,  $T_A=25^\circ C$ ,

Linearity from 0 to  $I_r$ ,  $T_A=25^\circ C$ ,

Electric Offset Voltage,  $T_A=25^\circ C$ ,

Magnetic Offset Voltage ( $I_r \rightarrow 0$ )

Thermal Drift of Offset Voltage,

Thermal Drift ( $-10^\circ C$  to  $50^\circ C$ ),

Response Time at 90% of  $I_p$  ( $f=1k$  Hz)

Frequency Bandwidth (-3dB),

Case Material:

$V_{cc}=+12V, +15V, +24V \pm 5\%$

$I_c < 25mA$

2.5kV, 50/60Hz, 1min

$R_{out} < 150\Omega$

$R_L > 10k\Omega$

$X < 1.0\% FS$

$E_L < 1.0\% FS$

$V_{oe} < 50mV$

$V_{om} < \pm 20mV$

$V_{of} < \pm 1.0mV/^\circ C$

T.C.  $< \pm 0.1\% /^\circ C$

$t_r < 200ms$

$f_b = 20Hz - 20kHz$

PBT



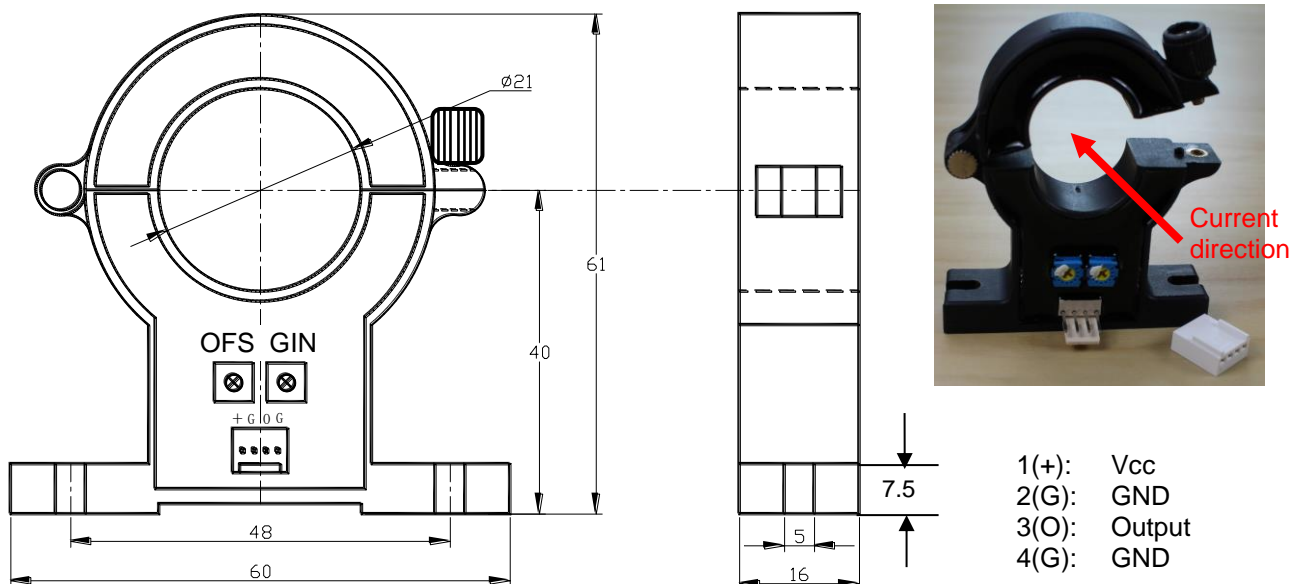


## General Data

Ambient Operating Temperature,  
Ambient Storage Temperature,

$T_A = -25^{\circ}\text{C} \sim +85^{\circ}\text{C}$   
 $T_S = -40^{\circ}\text{C} \sim +100^{\circ}\text{C}$

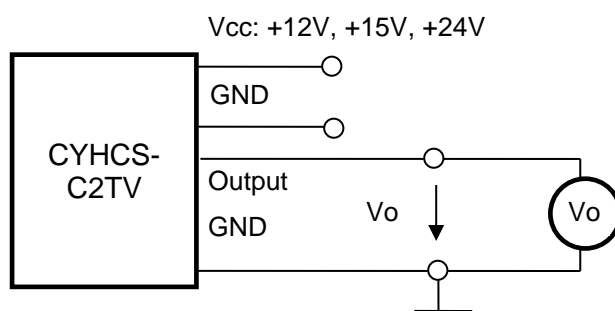
## PIN Definition and Dimensions



OFS: Offset Adjustment

GIN: Gain Adjustment

## Connection



## Notes:

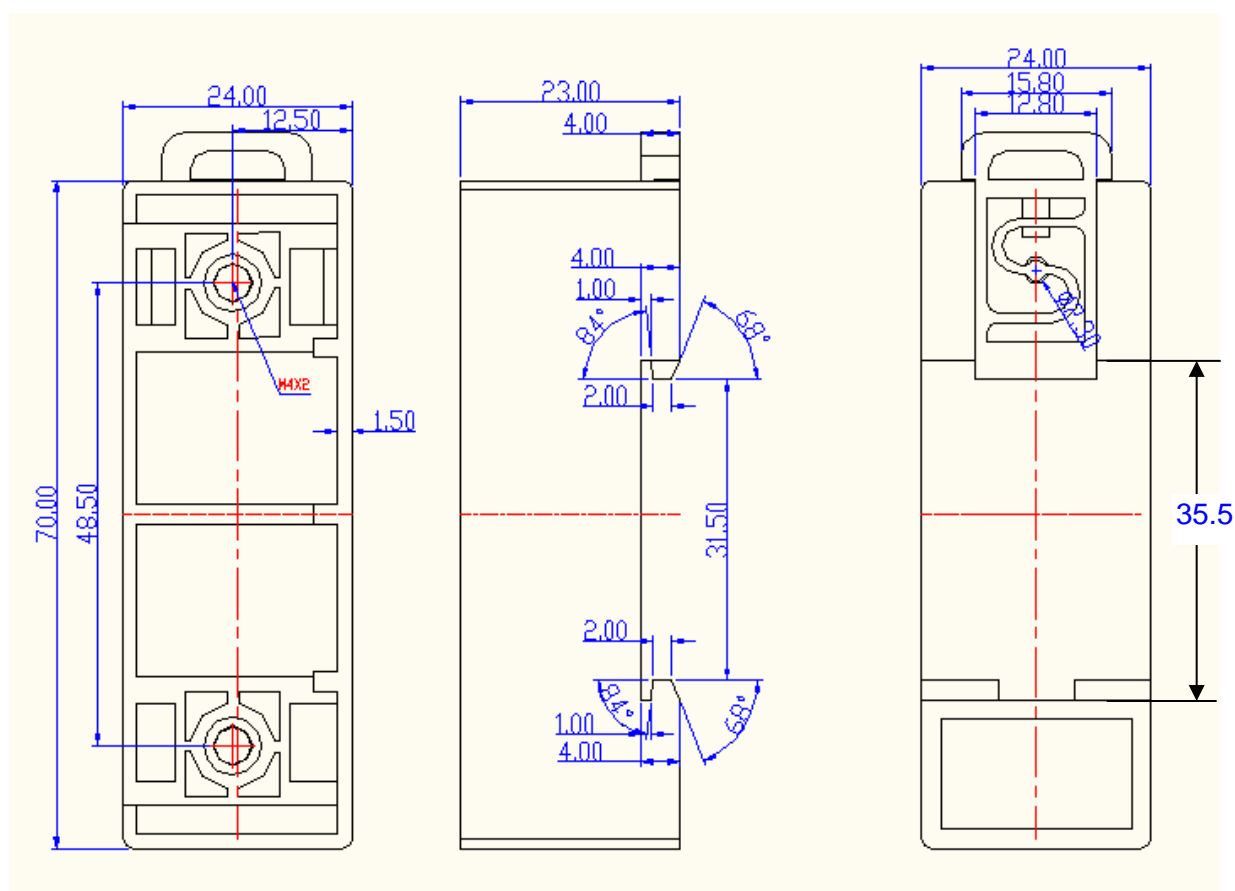
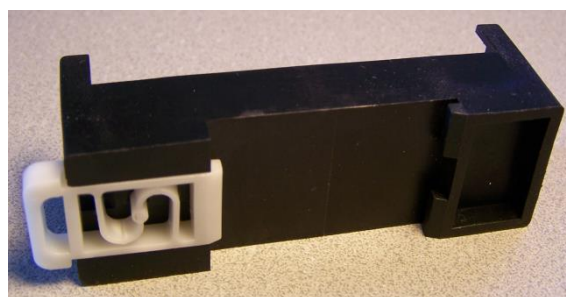
1. Connect the terminals of power source, output respectively and correctly, never make wrong connection.
2. Two potentiometers can be adjusted, only if necessary, by turning slowly to the required accuracy with a small screwdriver.
3. The best accuracy can be achieved when the window is fully filled with bus-bar (current carrying conductor).
4. The in-phase output can be obtained when the direction of current of current carrying conductor is the same as the direction of arrow marked on the transducer



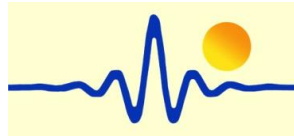


## DIN Rail Adapter CY-DRA88

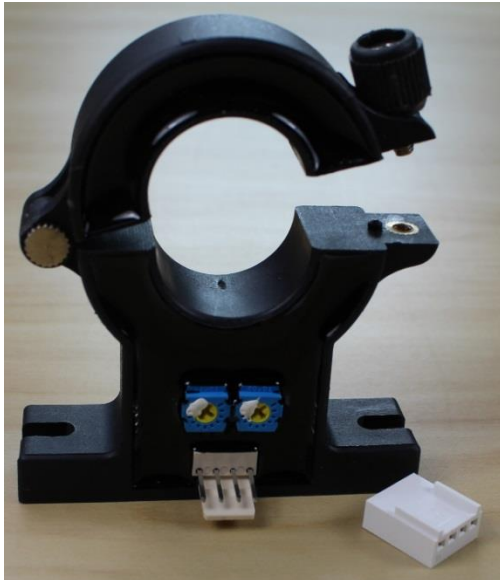
The DIN Rail Adapter CY-DRA88 is designed for mounting the sensor on 35mm DIN Rail. It has the size 70 x 24 x 23mm. The height from bottom to mounting surface is 14.8mm.







## Mounting of Sensors

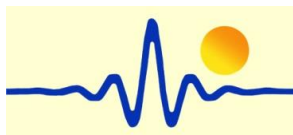


Sensor with Molex Connector  
(The distance between the bottom und the middle of hole is 54.8mm)



Sensor with Phoenix Connector  
(The distance between the bottom und the middle of hole is 54.8mm)





## Split Core Hall Effect AC Current Sensor CYHCS-EKADA

This Hall Effect current sensor is based on open loop principle and designed with a split core and a high galvanic isolation between primary conductor and secondary circuit. It can be used for measurement of AC current, pulse currents etc. The output of the transducer reflects the rectified average value of the current in the carrying conductor.

Product Characteristics	Applications
<ul style="list-style-type: none"> <li>• Excellent accuracy</li> <li>• Very good linearity</li> <li>• Using split cores and easy mounting</li> <li>• Less power consumption</li> <li>• Window structure</li> <li>• Electrically isolating the output of the transducer from the current carrying conductor</li> <li>• No insertion loss</li> <li>• Current overload capability</li> </ul>	<ul style="list-style-type: none"> <li>• <b>Photovoltaic equipment</b></li> <li>• Frequency conversion timing equipment</li> <li>• Various power supply</li> <li>• Uninterruptible power supplies (UPS)</li> <li>• Electric welding machines</li> <li>• Transformer substation</li> <li>• Numerical controlled machine tools</li> <li>• Electric powered locomotive</li> <li>• Microcomputer monitoring</li> <li>• Electric power network monitoring</li> </ul>

### Electrical Data

Primary Nominal RMS Current $I_r$ (A)	Measuring Range (A)	DC Output Current (mA)	Aperture Diameter (mm)	Part number
25	0 ~ 50	4-20 $\pm 1.0\%$	$\varnothing 21$	CYHCS-EKADA-25A-nC
30	0 ~ 60			CYHCS-EKADA-30A-nC
40	0 ~ 80			CYHCS-EKADA-40A-nC
50	0 ~ 100			CYHCS-EKADA-50A-nC
100	0 ~ 200			CYHCS-EKADA-100A-nC
200	0 ~ 400			CYHCS-EKADA-200A-nC
400	0 ~ 800			CYHCS-EKADA-400A-nC
500	0 ~ 1000			CYHCS-EKADA-500A-nC
600	0 ~ 1000			CYHCS-EKADA-600A-nC

(n=3,  $V_{cc} = +12VDC \pm 5\%$ ; n=4,  $V_{cc} = +15VDC \pm 5\%$ ; n=5,  $V_{cc} = +24VDC \pm 5\%$ )  
(Connector: Molex connector C=M; Phoenix Connector: C=P)

Supply Voltage	$V_{cc} = +12V, +15V, +24V \pm 5\%$
Current Consumption	$I_c < 25mA$
Galvanic isolation, 50/60Hz, 1min:	5kV
Isolation resistance @ 500 VDC	$> 500 M\Omega$
Accuracy at $I_r$ , $T_A = 25^\circ C$ ,	$X < 1.0\% FS$
Linearity from 0 to $I_r$ , $T_A = 25^\circ C$ ,	$E_L < 1.0\% FS$
Electric Offset Current, $T_A = 25^\circ C$ ,	4mA
Thermal Drift of Offset Current,	$< \pm 0.005 mA/^\circ C$
Response Time	$t_r < 200ms$
Frequency bandwidth (- 3 dB):	20Hz - 20kHz
Load resistance:	80-450 $\Omega$
Mean Time Between Failures (MTBF):	50k - 100k hours



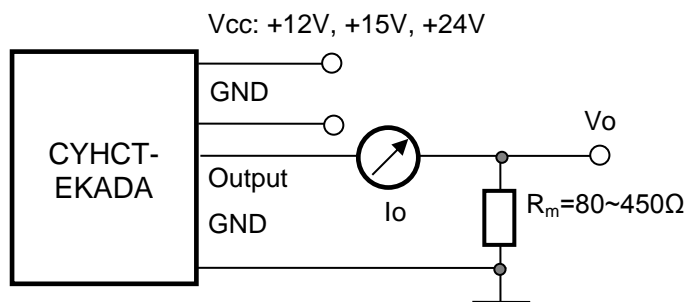
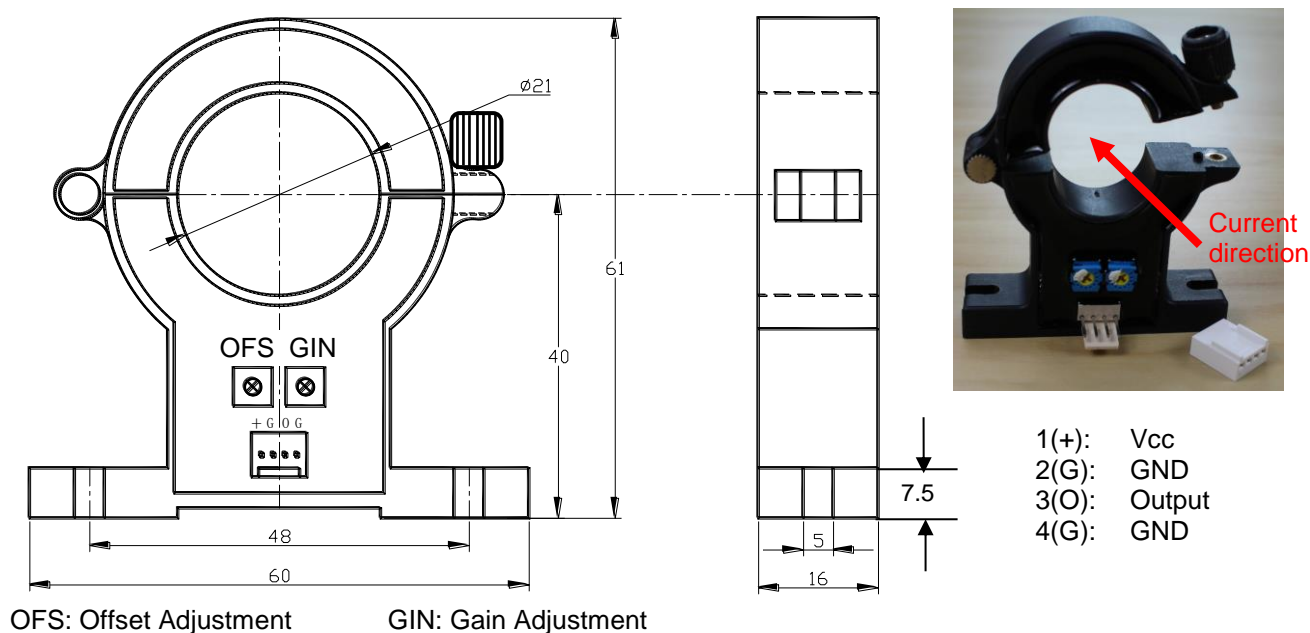


## General Data

Ambient Operating Temperature,  
Ambient Storage Temperature,

$T_A = -25^{\circ}\text{C} \sim +85^{\circ}\text{C}$   
 $T_S = -40^{\circ}\text{C} \sim +100^{\circ}\text{C}$

## PIN Definition and Dimensions



## Notes:

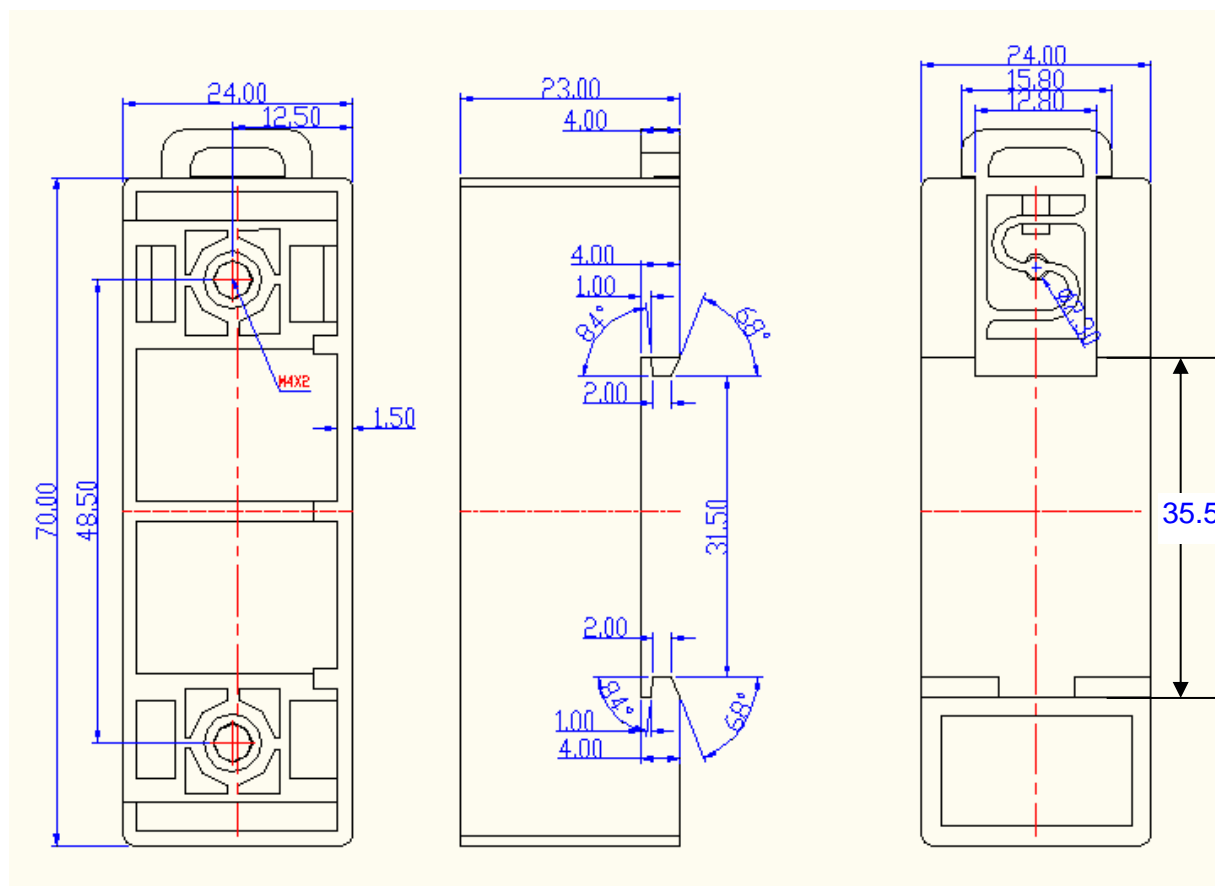
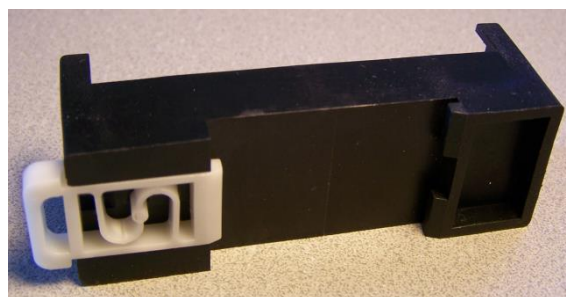
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3. The best accuracy can be achieved when the window is fully filled with bus-bar (current carrying conductor).
4. The in-phase output can be obtained when the direction of current of current carrying conductor is the same as the direction of arrow marked on the transducer



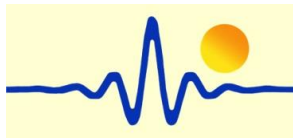


## DIN Rail Adapter CY-DRA88

The DIN Rail Adapter CY-DRA88 is designed for mounting the sensor on 35mm DIN Rail. It has the size 70 x 24 x 23mm. The height from bottom to mounting surface is 14.8mm.







## Mounting of Sensors

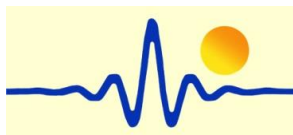


Sensor with Molex Connector  
(The distance between the bottom und the middle of hole is 54.8mm)



Sensor with Phoenix Connector  
(The distance between the bottom und the middle of hole is 54.8mm)





## Split Core Hall Effect AC Current Sensor CYHCS-EKAD

This Hall Effect current sensor is based on open loop principle and designed with a split core and a high galvanic isolation between primary conductor and secondary circuit. It can be used for measurement of AC current, pulse currents etc. The output of the transducer reflects the rectified average value of the current in the carrying conductor.

Product Characteristics	Applications
<ul style="list-style-type: none"> <li>Excellent accuracy</li> <li>Very good linearity</li> <li>Using split cores and easy mounting</li> <li>Less power consumption</li> <li>Window structure</li> <li>Electrically isolating the output of the transducer from the current carrying conductor</li> <li>No insertion loss</li> <li>Current overload capability</li> </ul>	<ul style="list-style-type: none"> <li><b>Photovoltaic equipment</b></li> <li>Frequency conversion timing equipment</li> <li>Various power supply</li> <li>Uninterruptible power supplies (UPS)</li> <li>Electric welding machines</li> <li>Transformer substation</li> <li>Numerical controlled machine tools</li> <li>Electric powered locomotive</li> <li>Microcomputer monitoring</li> <li>Electric power network monitoring</li> </ul>

### Electrical Data

Primary Nominal RMS Current $I_r$ (A)	Measuring Range RMS (A)	DC Output voltage (V)	Aperture Diameter (mm)	Part number
30	60	0-5 $\pm 1.0\%$	$\varnothing 21$	CYHCS-EKAD30A-C
50	100			CYHCS-EKAD50A-C
100	200			CYHCS-EKAD100A-C
200	400			CYHCS-EKAD200A-C
400	800			CYHCS-EKAD400A-C
500	1000			CYHCS-EKAD500A-C

(Connector: Molex connector C=M; Phoenix Connector: C=P)

Supply Voltage

Current Consumption

Galvanic isolation, 50/60Hz, 1min:

Load resistance:

Isolation resistance @ 500 VDC

$V_{cc} = \pm 15V \pm 5\%$ ,

$I_c < 25mA$

2.5kV

10k $\Omega$

> 500 M $\Omega$

### Accuracy and Dynamic performance data

Accuracy at  $I_r$ ,  $T_A = 25^\circ C$  (without offset),

Linearity from 0 to  $I_r$ ,  $T_A = 25^\circ C$ ,

Electric Offset Voltage,  $T_A = 25^\circ C$ ,

Thermal Drift of Offset Voltage,

Response Time at 90% of  $I_P$  ( $f = 1k$  Hz)

Frequency bandwidth (- 3 dB):

$X < 1.0\%$

$E_L < 1.0\%$  FS

$V_{oe} < 25mV$

$V_{ot} < \pm 0.5mV/^\circ C$

$t_r < 200ms$

20Hz - 20kHz

### General Data

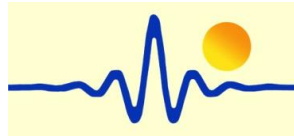
Ambient Operating Temperature,

Ambient Storage Temperature,

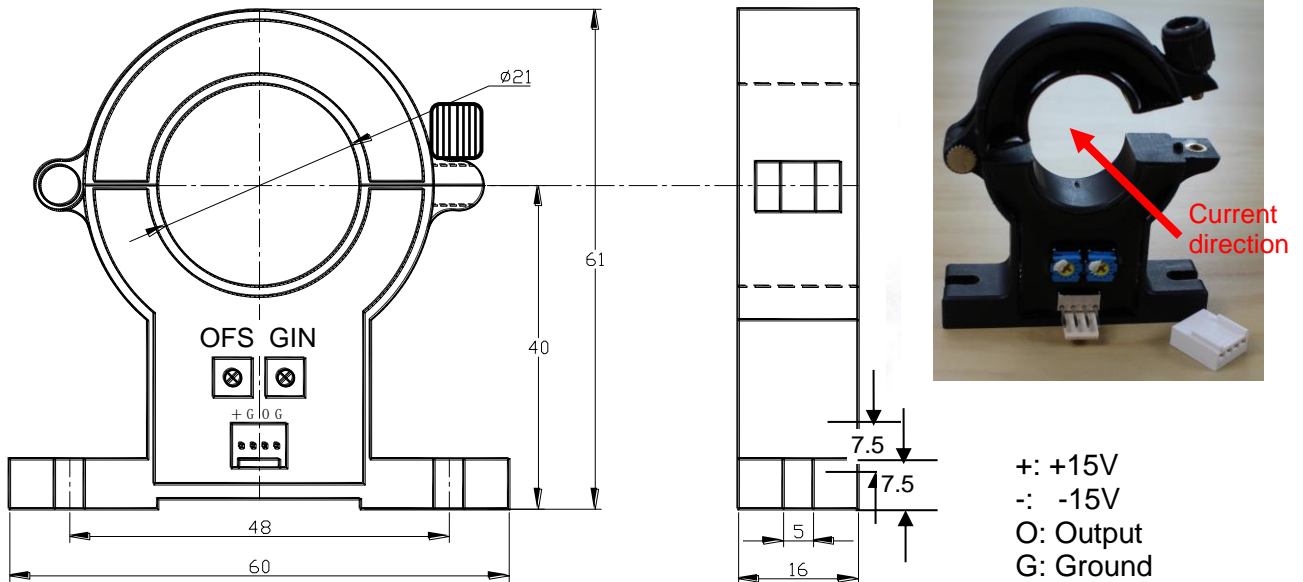
$T_A = -25^\circ C \sim +85^\circ C$

$T_S = -40^\circ C \sim +100^\circ C$

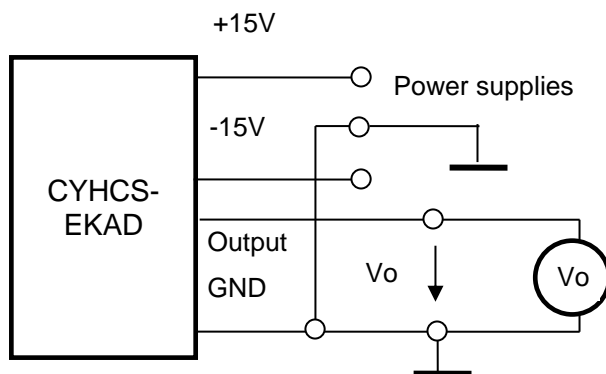




## PIN Definition and Dimensions



## Connection



## Notes:

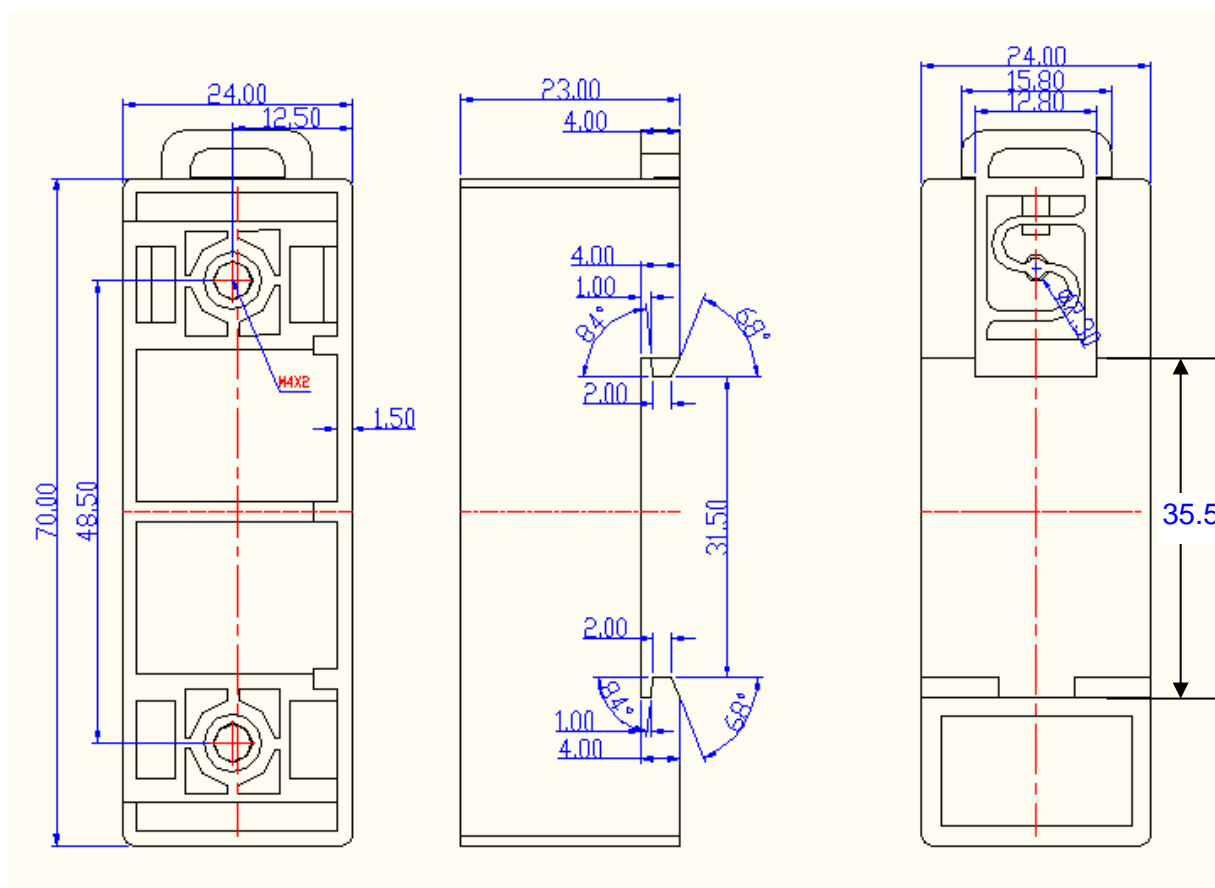
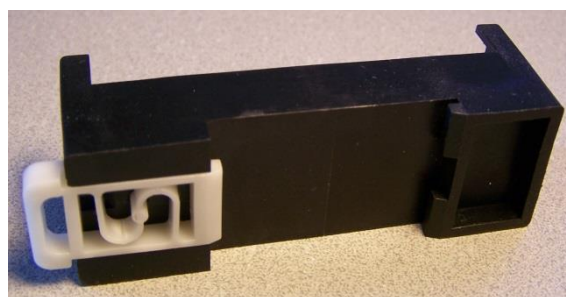
1. Connect the terminals of power source, output respectively and correctly, never make wrong connection.
2. Two potentiometers can be adjusted, only if necessary, by turning slowly to the required accuracy with a small screwdriver.
3. The best accuracy can be achieved when the window is fully filled with bus-bar (current carrying conductor).
4. The in-phase output can be obtained when the direction of current of current carrying conductor is the same as the direction of arrow marked on the transducer



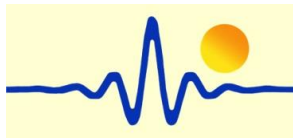


## DIN Rail Adapter CY-DRA88

The DIN Rail Adapter CY-DRA88 is designed for mounting the sensor on 35mm DIN Rail. It has the size 70 x 24 x 23mm. The height from bottom to mounting surface is 14.8mm.







## Mounting of Sensors

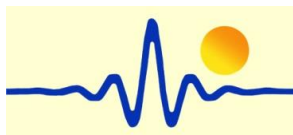


Sensor with Molex Connector  
(The distance between the bottom und the middle of hole is 54.8mm)



Sensor with Phoenix Connector  
(The distance between the bottom und the middle of hole is 54.8mm)





## Hall Effect AC Current Sensor CYHCS-D6V

This Hall Effect current sensor is based on open loop principle and designed with a solid core and a high galvanic isolation between primary conductor and secondary circuit. It can be used for measurement of AC current etc. The output of the transducer reflects the rectified average value of the current in the carrying conductor.

Product Characteristics	Applications
<ul style="list-style-type: none"> <li>Excellent accuracy</li> <li>Very good linearity</li> <li>Using split cores and easy mounting</li> <li>Less power consumption</li> <li>Window structure</li> <li>Electrically isolating the output of the transducer from the current carrying conductor</li> <li>No insertion loss</li> <li>Current overload capability</li> </ul>	<ul style="list-style-type: none"> <li><b>Photovoltaic equipment</b></li> <li>Frequency conversion timing equipment</li> <li>Various power supply</li> <li>Uninterruptible power supplies (UPS)</li> <li>Electric welding machines</li> <li>Transformer substation</li> <li>Numerical controlled machine tools</li> <li>Electric powered locomotive</li> <li>Microcomputer monitoring</li> <li>Electric power network monitoring</li> </ul>

### Electrical Data

Primary Nominal rms Current $I_r$ (A)	Measuring Range (A)	DC Output Voltage (V)	Part number
50	0 ~ ±50A	x=0: 0-4V ±1.0% x=3: 0-5V ±1.0% x=8: 0-10V ±1.0%	CYHCS-D6V-50A-xn
100	0 ~ ±100A		CYHCS-D6V-100A-xn
200	0 ~ ±200A		CYHCS-D6V-200A-xn
300	0 ~ ±300A		CYHCS-D6V-300A-xn
400	0 ~ ±400A		CYHCS-D6V-400A-xn
500	0 ~ ±500A		CYHCS-D6V-500A-xn
600	0 ~ ±600A		CYHCS-D6V-600A-xn
700	0 ~ ±700A		CYHCS-D6V-700A-xn
800	0 ~ ±800A		CYHCS-D6V-800A-xn
900	0 ~ ±900A		CYHCS-D6V-900A-xn
1000	0 ~ ±1000A		CYHCS-D6V-1000A-xn

(n=2,  $V_{cc}$ = +12VDC ±5%; n=3,  $V_{cc}$ =+15VDC ±5%; n=4,  $V_{cc}$ =+24VDC±5%)

Supply Voltage:	$V_{cc}$ =+12V, +15V, +24V± 5%
Current Consumption	$I_c$ < 25mA
Isolation Voltage	2.5kV, 50/60Hz, 1min
Output Voltage at $I_r$ , $T_A$ =25°C:	$V_{out}$ =0- 4V, 0-5V, 0-10VDC
Output Impedance:	$R_{out}$ < 150Ω
Load Resistor:	$R_L$ > 10kΩ
Accuracy at $I_r$ , $T_A$ =25°C,	$X$ <1.0% FS
Linearity from 0 to $I_r$ , $T_A$ =25°C,	$E_L$ <1.0% FS
Electric Offset Voltage, $T_A$ =25°C,	$V_{oe}$ <50mV
Magnetic Offset Voltage ( $I_r$ →0)	$V_{om}$ <±20mV
Thermal Drift of Offset Voltage,	$V_{ot}$ <±1.0mV/°C



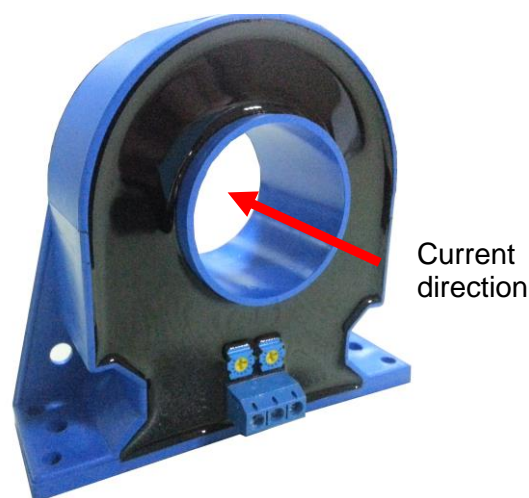
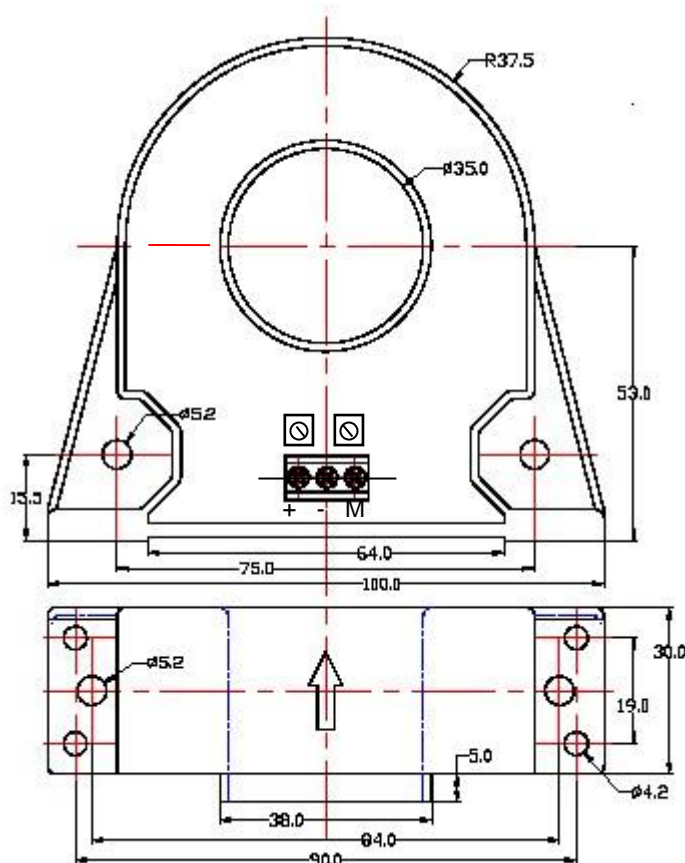


Thermal Drift ( $-10^{\circ}\text{C}$  to  $50^{\circ}\text{C}$ ),  
Response Time at 90% of  $I_p$  ( $f=1\text{ kHz}$ )  
Frequency Bandwidth ( $-3\text{ dB}$ ),  
Case Material:  
Ambient Operating Temperature,  
Ambient Storage Temperature,

T.C.  $< \pm 0.1\% / ^{\circ}\text{C}$   
 $t_r < 200\text{ ms}$   
 $f_b = 20\text{ Hz} - 20\text{ kHz}$   
PBT  
 $T_A = -25^{\circ}\text{C} \sim +85^{\circ}\text{C}$   
 $T_S = -40^{\circ}\text{C} \sim +100^{\circ}\text{C}$

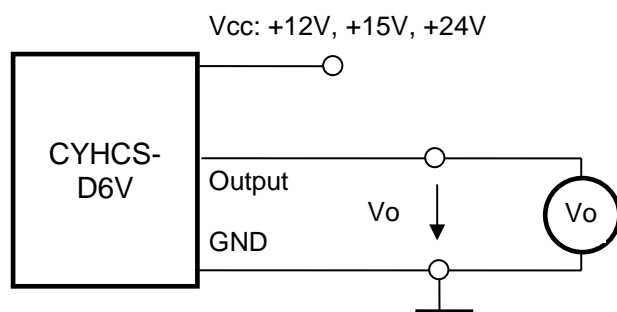
## PIN Definition and Dimensions

### CYHCS-D6V-xxxx



#### Terminal Arrangement

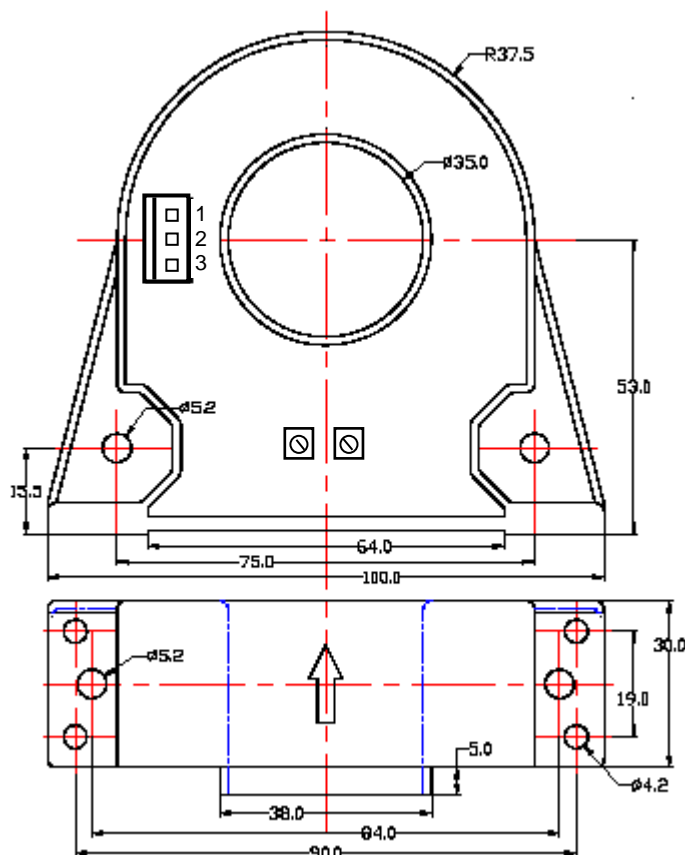
1(+):  $V_{CC}$   
2(-): GND  
3(M): Output





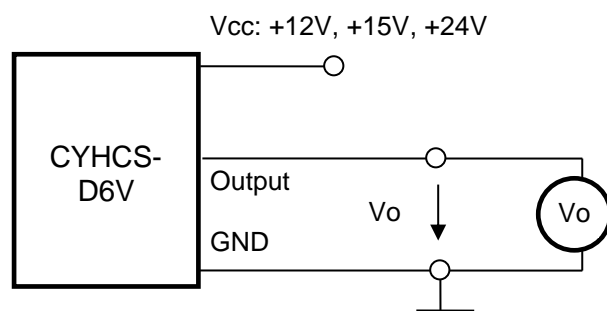


## CYHCS-D6V-xxxx



### Terminal Arrangement

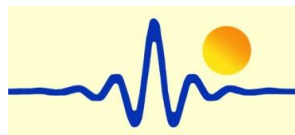
- |    |        |
|----|--------|
| 1: | Vcc    |
| 2: | GND    |
| 3: | Output |



### Notes:

1. Connect the terminals of power source, output respectively and correctly, never make wrong connection.
2. Two potentiometers can be adjusted, only if necessary, by turning slowly to the required accuracy with a small screwdriver.
3. The best accuracy can be achieved when the window is fully filled with bus-bar (current carrying conductor).
4. The in-phase output can be obtained when the direction of current of current carrying conductor is the same as the direction of arrow marked on the transducer





## Hall Effect AC Current Sensor CYHCS-D6C

This Hall Effect current sensor is based on open loop principle and designed with a high galvanic isolation between primary conductor and secondary circuit. It can be used for measurement of AC current etc. The output of the transducer reflects the rectified average value of the current in the carrying conductor.

Product Characteristics	Applications
<ul style="list-style-type: none"> <li>• Excellent accuracy</li> <li>• Very good linearity</li> <li>• Using split cores and easy mounting</li> <li>• Less power consumption</li> <li>• Window structure</li> <li>• Electrically isolating the output of the transducer from the current carrying conductor</li> <li>• No insertion loss</li> <li>• Current overload capability</li> </ul>	<ul style="list-style-type: none"> <li>• <b>Photovoltaic equipment</b></li> <li>• Frequency conversion timing equipment</li> <li>• Various power supply</li> <li>• Uninterruptible power supplies (UPS)</li> <li>• Electric welding machines</li> <li>• Transformer substation</li> <li>• Numerical controlled machine tools</li> <li>• Electric powered locomotive</li> <li>• Microcomputer monitoring</li> <li>• Electric power network monitoring</li> </ul>

### Electrical Data

Primary Nominal rms Current $I_r$ (A)	Measuring Range (A)	DC Output Current $I_s$ (mA)	Part number
50	0 ~ ±50A	4-20 ±1.0%	CYHCS-D6C-50A-n
100	0 ~ ±100A		CYHCS-D6C-100A-n
200	0 ~ ±200A		CYHCS-D6C-200A-n
300	0 ~ ±300A		CYHCS-D6C-300A-n
400	0 ~ ±400A		CYHCS-D6C-400A-n
500	0 ~ ±500A		CYHCS-D6C-500A-n
600	0 ~ ±600A		CYHCS-D6C-600A-n
700	0 ~ ±700A		CYHCS-D6C-700A-n
800	0 ~ ±800A		CYHCS-D6C-800A-n
900	0 ~ ±900A		CYHCS-D6C-900A-n
1000	0 ~ ±1000A		CYHCS-D6C-1000A-n

(n=3,  $V_{cc}$ = +12VDC ±5%; n=4,  $V_{cc}$ =+15VDC ±5%; n=5,  $V_{cc}$ =+24VDC±5%)

Supply Voltage	$V_{cc}$ = +12V, +15V, +24V ± 5%,
Current Consumption	$I_c$ < 25mA + $I_s$
Galvanic isolation, 50/60Hz, 1min:	5kV
Isolation resistance @ 500 VDC	> 500 MΩ
Accuracy at $I_r$ , $T_A$ =25°C,	$X$ <1.0% FS
Linearity from 0 to $I_r$ , $T_A$ =25°C,	$E_L$ <1.0% FS
Electric Offset Current, $T_A$ =25°C,	4mA
Thermal Drift of Offset Current,	<±0.005mA/°C
Response Time at 90% of $I_P$ ( $f$ =1k Hz)	$t_r$ < 200ms
Frequency bandwidth (- 3 dB):	20Hz - 20kHz
Load resistance:	80-450Ω
Mean Time Between Failures (MTBF):	50k - 100k hours



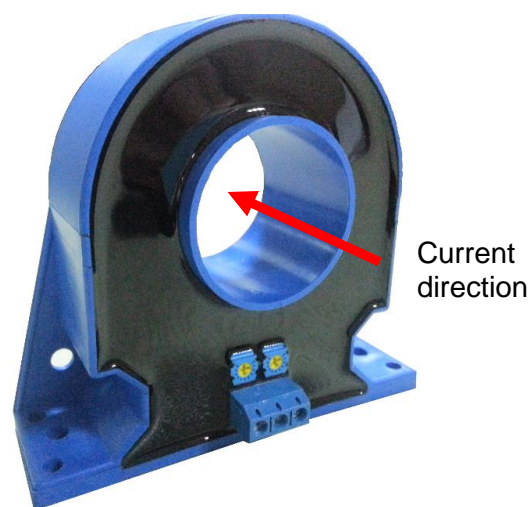
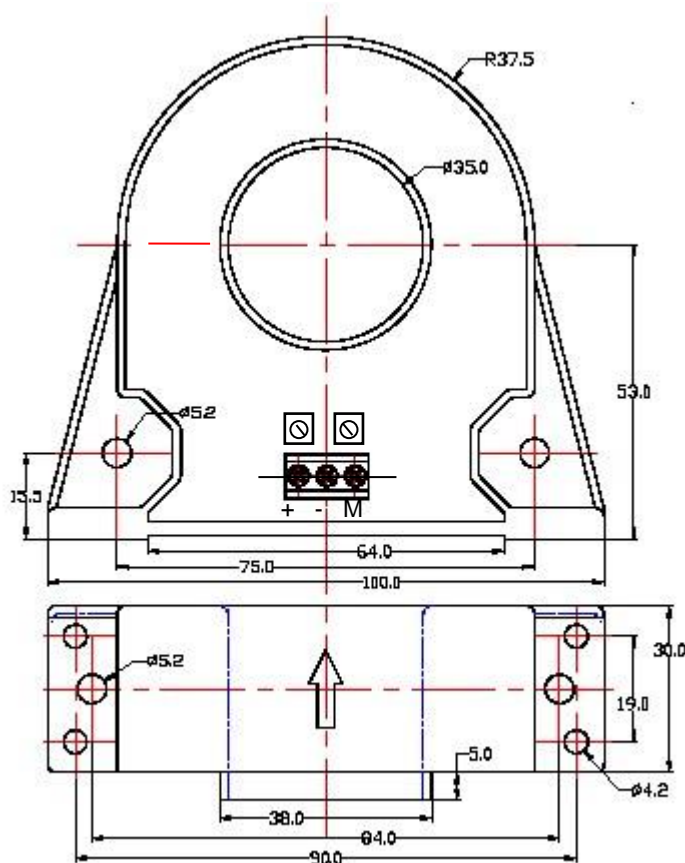


Ambient Operating Temperature,  
Ambient Storage Temperature,

$T_A = -25^{\circ}\text{C} \sim +85^{\circ}\text{C}$   
 $T_S = -40^{\circ}\text{C} \sim +100^{\circ}\text{C}$

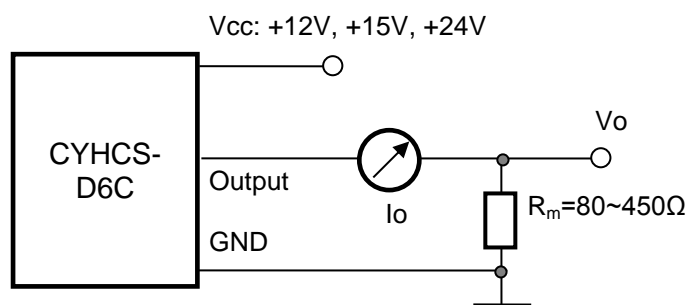
## PIN Definition and Dimensions

### CYHCS-D6C-xxxx



#### Terminal Arrangement

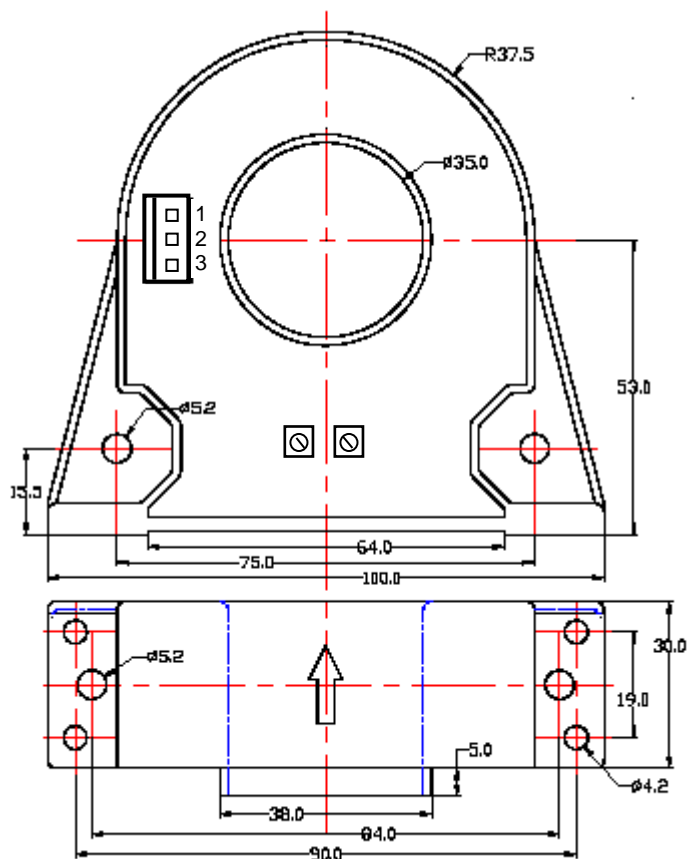
1(+):  $V_{CC}$   
2(-): GND  
3(M): Output





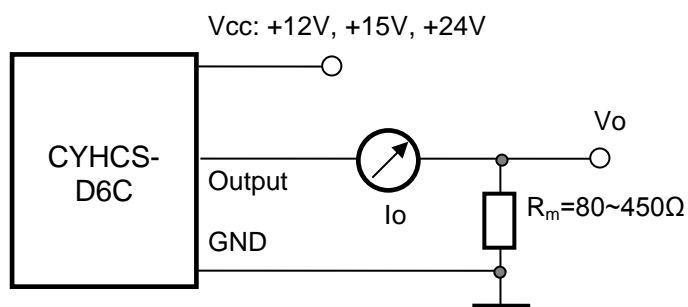


## CYHCS-D6C-xxxx



### Terminal Arrangement

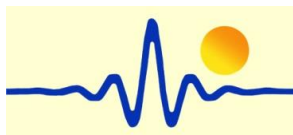
- |    |        |
|----|--------|
| 1: | Vcc    |
| 2: | GND    |
| 3: | Output |



### Notes:

1. Connect the terminals of power source, output respectively and correctly, never make wrong connection.
2. Two potentiometers can be adjusted, only if necessary, by turning slowly to the required accuracy with a small screwdriver.
3. The best accuracy can be achieved when the window is fully filled with bus-bar (current carrying conductor).
4. The in-phase output can be obtained when the direction of current of current carrying conductor is the same as the direction of arrow marked on the transducer





## Split Core Hall Effect AC Current Sensor CYHCS-C3TV

This Hall Effect current sensor is based on open loop principle and designed with a split core and a high galvanic isolation between primary conductor and secondary circuit. It can be used for measurement of AC current, pulse currents etc. The output of the transducer reflects the rectified average value of the current in the carrying conductor.

Product Characteristics	Applications
<ul style="list-style-type: none"> <li>Excellent accuracy</li> <li>Very good linearity</li> <li>Light in weight</li> <li>Less power consumption</li> <li>Window structure</li> <li>Electrically isolating the output of the transducer from the current carrying conductor</li> <li>No insertion loss</li> <li>Current overload capability</li> </ul>	<ul style="list-style-type: none"> <li><b>Photovoltaic equipment</b></li> <li>Frequency conversion timing equipment</li> <li>Various power supply</li> <li>Uninterruptible power supplies (UPS)</li> <li>Electric welding machines</li> <li>Numerical controlled machine tools</li> <li>Electrolyzing and electroplating equipment</li> <li>Electric powered locomotive</li> <li>Microcomputer monitoring</li> <li>Electric power network monitoring</li> </ul>

### Electrical Data

Primary Nominal Current $I_r$ (A), rms	Primary Current Measuring Range $I_p$ (A)	DC Output Voltage (V)	Part number
50A	0 ~ 50A	$x=0$ : 0-4V $\pm 1.0\%$ $x=3$ : 0-5V $\pm 1.0\%$ $x=8$ : 0-10V $\pm 1.0\%$	CYHCS-C3TV-50A-xnC
100A	0 ~ 100A		CYHCS-C3TV-100A-xnC
200A	0 ~ 200A		CYHCS-C3TV-200A-xnC
300A	0 ~ 300A		CYHCS-C3TV-300A-xnC
400A	0 ~ 400A		CYHCS-C3TV-400A-xnC
500A	0 ~ 500A		CYHCS-C3TV-500A-xnC
800A	0 ~ 800A		CYHCS-C3TV-800A-xnC
1000A	0 ~ 1000A		CYHCS-C3TV-1000A-xnC
1500A	0 ~ 1500A		CYHCS-C3TV-1500A-xnC
2000A	0 ~ 2000A		CYHCS-C3TV-2000A-xnC

( $n=2$ ,  $V_{cc}=+12VDC$ ;  $n=3$ ,  $V_{cc}=+15VDC$ ;  $n=4$ ,  $V_{cc}=+24VDC$ )

(Connector: Molex connector C=M; Phoenix Connector: C=P)

Supply Voltage:

$V_{cc}=+12V, +15V, +24V \pm 5\%$

Current Consumption

$I_c < 25mA$

Isolation Voltage

5kV, 50/60Hz, 1min

Output Impedance:

$R_{out} < 150\Omega$

Load Resistor:

$R_L > 10k\Omega$

Accuracy at  $I_r$ ,  $T_A=25^\circ C$ ,

$X < 1.0\% FS$

Linearity from 0 to  $I_r$ ,  $T_A=25^\circ C$ ,

$E_L < 1.0\% FS$

Electric Offset Voltage,  $T_A=25^\circ C$ ,

$V_{oe} < 50mV$

Magnetic Offset Voltage ( $I_r \rightarrow 0$ )

$V_{om} < \pm 20mV$

Thermal Drift of Offset Voltage,

$V_{ot} < \pm 1.0mV/^\circ C$

Thermal Drift ( $-10^\circ C$  to  $50^\circ C$ ),

T.C.  $< \pm 0.1\% / ^\circ C$

Response Time at 90% of  $I_p$  ( $f=1k Hz$ )

$t_r < 200ms$

Frequency Bandwidth (-3dB),

$f_b = 20Hz - 20 kHz$

Case Material:

PBT, heat resistant  $125^\circ C$  flame retardant



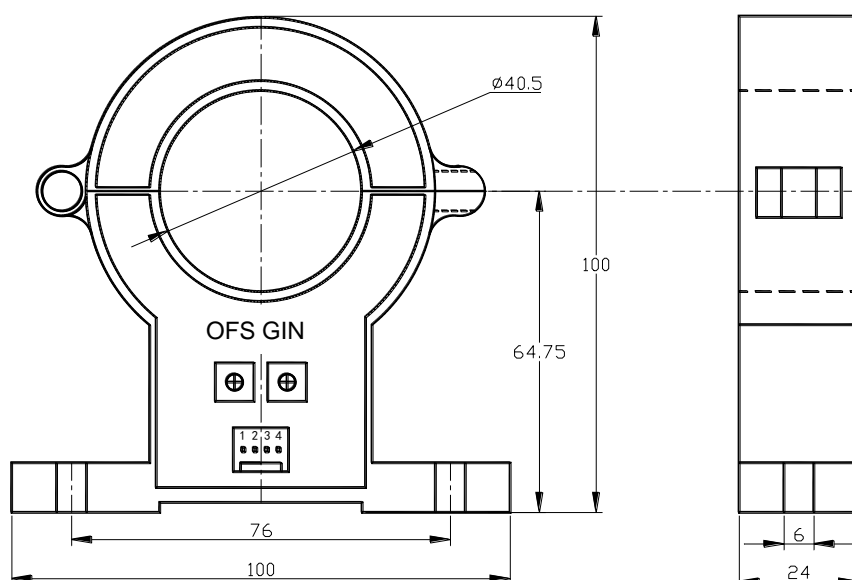


## General Data

Ambient Operating Temperature,  
Ambient Storage Temperature,

$T_A = -25^{\circ}\text{C} \sim +85^{\circ}\text{C}$   
 $T_S = -40^{\circ}\text{C} \sim +100^{\circ}\text{C}$

## PIN Definition and Dimensions



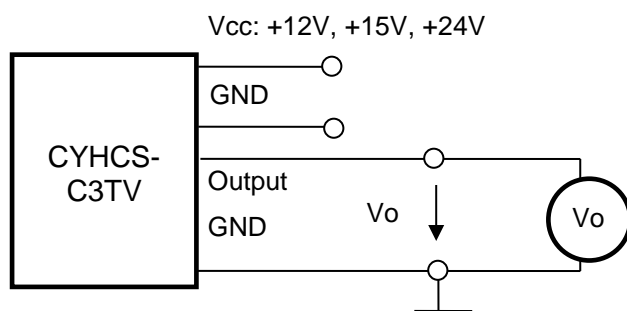
OFS: Offset Adjustment

GIN: Gain Adjustment



1(+): Vcc  
2(G): GND  
3(O): Output  
4(G): GND

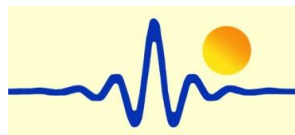
## Connection



## Notes:

1. Connect the terminals of power source, output respectively and correctly, never make wrong connection.
2. Two potentiometers can be adjusted, only if necessary, by turning slowly to the required accuracy with a small screwdriver.
3. The best accuracy can be achieved when the window is fully filled with bus-bar (current carrying conductor).
4. The in-phase output can be obtained when the direction of current of current carrying conductor is the same as the direction of arrow marked on the transducer





## Split Core Hall Effect AC Current Sensor CYHCS-EKBDA

This Hall Effect current sensor is based on open loop principle and designed with a split core and a high galvanic isolation between primary conductor and secondary circuit. It can be used for measurement of AC current, pulse currents etc. The output of the transducer reflects the rectified average value of the current in the carrying conductor.

Product Characteristics	Applications
<ul style="list-style-type: none"> <li>• Excellent accuracy</li> <li>• Very good linearity</li> <li>• Using split cores and easy mounting</li> <li>• Less power consumption</li> <li>• Window structure</li> <li>• Electrically isolating the output of the transducer from the current carrying conductor</li> <li>• No insertion loss</li> <li>• Current overload capability</li> </ul>	<ul style="list-style-type: none"> <li>• <b>Photovoltaic equipment</b></li> <li>• Frequency conversion timing equipment</li> <li>• Various power supply</li> <li>• Uninterruptible power supplies (UPS)</li> <li>• Electric welding machines</li> <li>• Transformer substation</li> <li>• Numerical controlled machine tools</li> <li>• Electric powered locomotive</li> <li>• Microcomputer monitoring</li> <li>• Electric power network monitoring</li> </ul>

### Electrical Data

Primary Nominal RMS Current $I_r$ (A)	Measuring Range (A)	DC Output Current (mA)	Aperture Diameter (mm)	Part number
50	0 ~ 50	4-20 $\pm$ 1.0%	$\varnothing$ 40.5	CYHCS-EKBDA-50A-nC
100	0 ~ 100			CYHCS-EKBDA-100A-nC
200	0 ~ 200			CYHCS-EKBDA-200A-nC
500	0 ~ 500			CYHCS-EKBDA-500A-nC
800	0 ~ 800			CYHCS-EKBDA-800A-nC
1000	0 ~ 1000			CYHCS-EKBDA-1000A-nC
1500	0 ~ 1500			CYHCS-EKBDA-1500A-nC
2000	0 ~ 2000			CYHCS-EKBDA-2000A-nC

(n=3,  $V_{cc}$ = +12VDC  $\pm$ 5%; n=4,  $V_{cc}$  =+15VDC  $\pm$ 5%; n=5,  $V_{cc}$  =+24VDC $\pm$ 5%)

(Connector: Molex connector C=M; Phoenix Connector: C=P)

Supply Voltage

$V_{cc}$ =+12V, +15V, +24V  $\pm$  5%

Current Consumption

$I_c$  < 25mA

Galvanic isolation, 50/60Hz, 1min:

5kV

Isolation resistance @ 500 VDC

> 500 M $\Omega$

### Accuracy and Dynamic performance data

Accuracy at  $I_r$ ,  $T_A$ =25°C,

$X$  <1.0% FS

Linearity from 0 to  $I_r$ ,  $T_A$ =25°C,

$E_L$  <1.0% FS

Electric Offset Current,  $T_A$ =25°C,

4mA

Thermal Drift of Offset Current,

< $\pm$ 0.005mA/°C

Response Time

$t_r$  < 200ms

Frequency bandwidth (- 3 dB):

20Hz - 20kHz

Load resistance:

80-450 $\Omega$



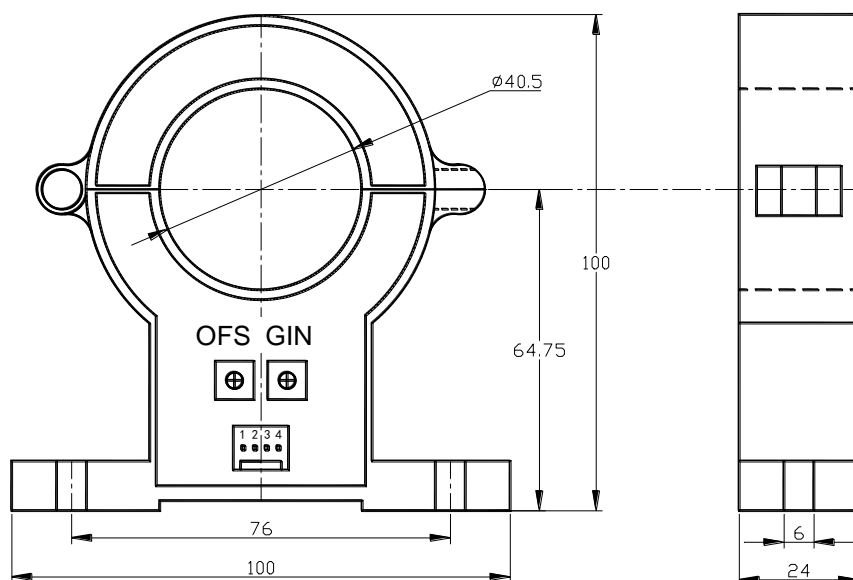


## General Data

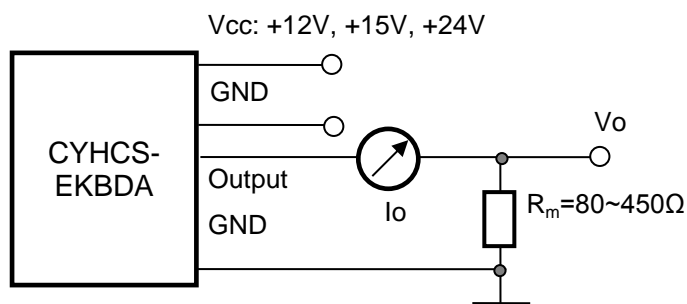
Ambient Operating Temperature,  
Ambient Storage Temperature,

$T_A = -25^{\circ}\text{C} \sim +85^{\circ}\text{C}$   
 $T_S = -40^{\circ}\text{C} \sim +100^{\circ}\text{C}$

## PIN Definition and Dimensions



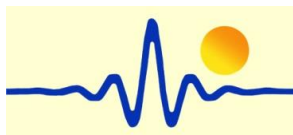
1(+): Vcc  
2(G): NC (GND)  
3(O): Output  
4(G): GND



## Notes:

1. Connect the terminals of power source, output respectively and correctly, never make wrong connection.
2. Two potentiometers can be adjusted, only if necessary, by turning slowly to the required accuracy with a small screwdriver.
3. The best accuracy can be achieved when the window is fully filled with bus-bar (current carrying conductor).
4. The in-phase output can be obtained when the direction of current of current carrying conductor is the same as the direction of arrow marked on the transducer





## Hall Effect AC Current Sensor CYHCS-WF3

The sensor CYHCS-WF3 is an open loop Hall Effect Sensor for the measurement of AC current. The sensor has a galvanic isolation between the primary conductor and the secondary electronic circuit.

Features and Advantages	Applications
<ul style="list-style-type: none"> <li>DC current measurement</li> <li>Output signal option (0-20mA, 4-20mA, 0-5V, <math>\pm 5V</math>, 0-10V)</li> <li>35mm DIN Rail</li> <li>High isolation between primary and secondary circuits</li> <li>No insertion losses</li> <li>Easy installation</li> </ul>	<ul style="list-style-type: none"> <li><b>Photovoltaic equipment</b></li> <li>Battery banks, such as, monitoring load current and charge current, verifying operation</li> <li>Transportation, measuring traction power or auxiliary loads</li> <li>Phase fired controlled heaters</li> <li>Directly connect to PLC</li> <li>Sense motor stalls and short circuits</li> </ul>

## Specifications

Rated input current (DC current calibration)	50A ~ 800A
Linear measuring range	0-60A ~ 0-960A
Overload current capability	20 times of rated input current, 5sec
Output signals	$\pm 5VDC$ , 0-5VDC, 0-10VDC, 0-20mADC, 4-20mADC
Power supply (voltage Ripple)	+12V DC, +24V DC, $\pm 12V$ DC, $\pm 15V$ DC (5%)
Measuring accuracy	$\pm 1.0\%$
Linearity (10% - 100%), 25°C	$\leq \pm 0.5\%$ FS
Zero offset voltage	$\pm 25mV$
Thermal drift of offset voltage	$\leq \pm 0.04\%/^{\circ}C$
Galvanic isolation	6 kV AC, 50Hz, 1min
Isolation resistance	$\geq 100M\Omega$
Response time	$\leq 20\mu s$ for tracing output, $\leq 100ms$ DC voltage output, $\leq 150ms$ DC current output,
di/dt following accuracy	50A/ $\mu s$
Current consumption	$\leq 50mA$
Output load	Voltage output : $\geq 2k\Omega$ , Current output: $\leq 250\Omega$
Frequency range	25Hz ~ 5kHz
Case style and Window size	WF3 , $\Phi 35mm$
Operating temperature	-25°C ~ +70°C
Storage temperature	-45°C ~ + 85°C
Relative humidity	$\leq 90\%$
MTBF	>50000h
Unit weight	200g

## Definition of Part number:

CYHCS	-	WF3	-	m	-	x	n
(1)		(2)		(3)		(4)	(5)





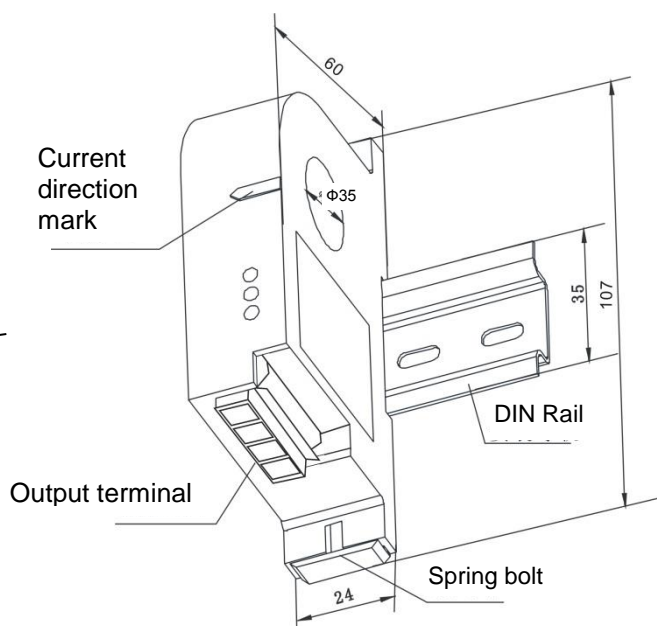
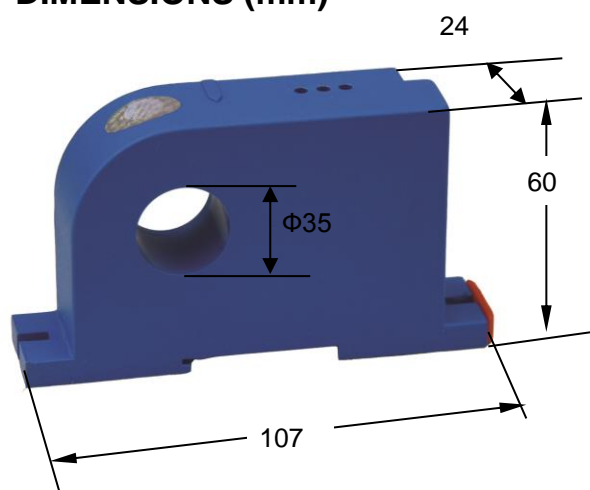
(1)	(2)	(3)	(4)	(5)
Series name	Case style	Rated Input current (m)	Output signal	Power supply
CYHCS	WF3	m = 50A, 100A, 200A, 300A, 400A, 500A, 600A, 700A, 800A	<b>x=1:</b> tracing voltage $\pm 5V$ DC <b>x=3:</b> 0-5V DC <b>x=4:</b> 0-20mA DC <b>x=5:</b> 4-20mA DC <b>x=8:</b> 0-10V DC	<b>n=2:</b> +12V DC <b>n=4:</b> +24V DC <b>n=5:</b> $\pm 12V$ DC <b>n=6:</b> $\pm 15V$ DC

**Example 1:** CYHCS-WF3-400A -15, Hall Effect AC Current sensor with  
Output signal: tracing voltage  $\pm 5V$  AC  
Power supply:  $\pm 12V$  DC  
Rated input current: 400A AC

**Example 2:** CYHCS-WF3-400A -14, Hall Effect AC Current sensor with  
Output signal: tracing voltage  $\pm 5V$  AC  
Power supply: +24V DC  
Rated input current: 400A AC

**Example 3:** CYHCS-WF3-400A -54, Hall Effect AC Current sensor with  
Output signal: 4-20mA DC  
Power supply: +24V DC  
Rated input current: 400A AC

## DIMENSIONS (mm)



Dimensions: 107x 24 x 60mm, Aperture:  $\varnothing 35$  mm

### Pin Arrangement:

+: V+                      -: V- (or NC)  
OUT: Output              GND: Ground





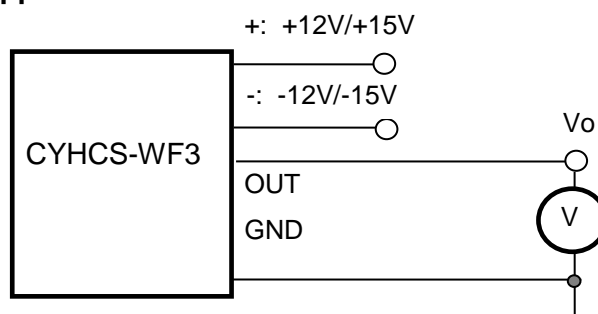
## CONNECTIONS

The current carrying cable must pass through the window. The phase of output is the same as that of the current passing the window in the direction of the arrow indicated on the case.

### a) Wiring of Sensors Using Double Power Supplies

#### Voltage Output

+: +15V/+12V  
OUT: Output  
GND: Ground  
-: -15V/-12V

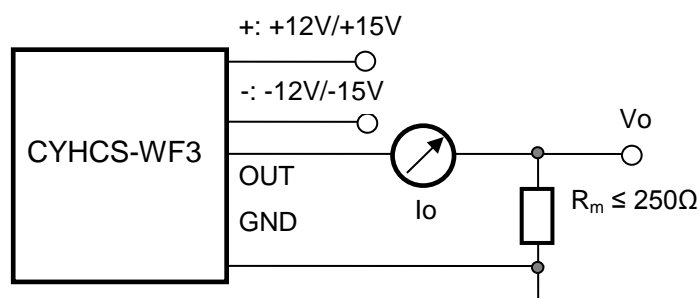


Relation between Input and Output:

Sensor CYHCS-WF3-400A-15	
Input current (A)	Output voltage (V)
-400	-5
-200	-2.5
0	0
200	2.5
400	5

#### Current Output

+: +12V/+15V  
OUT: Output  
GND: Ground  
-: -12V/-15V



Relation between Input and Output (for  $R_m=250\ \Omega$ ):

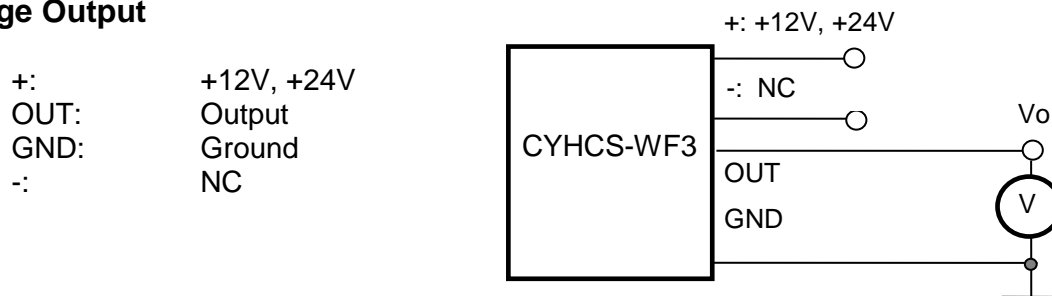
Sensor CYHCS-WF3-400A-55		
Input current (A)	Output current $I_o$ (mA, DC)	Output voltage $V_o$ (V, DC)
0	4	1
100	8	2
200	12	3
300	16	4
400	20	5





## B) Wiring of Sensors Using Single Power Supply

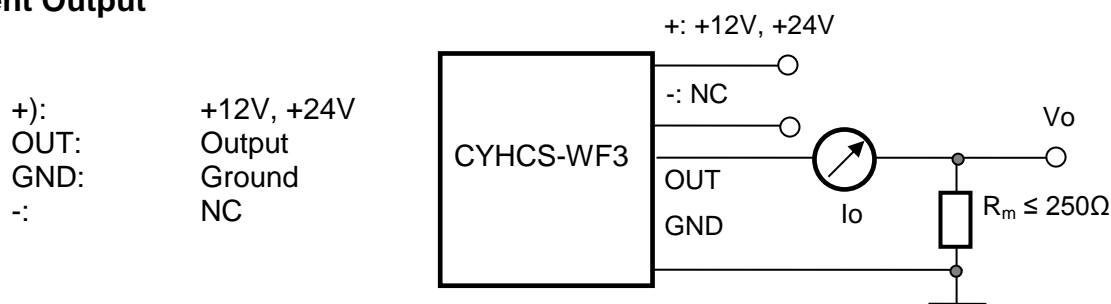
### Voltage Output



Relation between Input and Output:

Sensor CYHCS-WF3-400A-14	
Input current (A)	Output voltage (V)
-400	-5
-200	-2.5
0	0
200	2.5
400	5

### Current Output



Relation between Input and Output (for  $R_m=250\Omega$ ):

Sensor CYHCS-WF3-400A-54		
Input current (A)	Output current $I_o$ (mA, DC)	Output voltage $V_o$ (V, DC)
0	4	1
100	8	2
200	12	3
300	16	4
400	20	5

### Notes:

1. Connect the terminals of power source, output respectively and correctly, never make wrong connection.
2. Two potentiometers can be adjusted, only if necessary, by turning slowly to the required accuracy with a small screwdriver.
3. The best accuracy can be achieved when the window is fully filled with bus-bar (current carrying conductor).
4. The in-phase output can be obtained when the direction of current of current carrying conductor is the same as the direction of arrow marked on the transducer case.